

# Richard Barabasi

If you have time, please visit my portfolio site for in depth details |  
You will find my skills and conducted projects in navigable and sortable structure |  
<https://picsiri.github.io> |

## Personal data

Date of birth: 1996.05.11.

Address: 1203. Budapest, Vízisport utca 5 2/2

Email: [barabasi.richard@gmail.com](mailto:barabasi.richard@gmail.com)

Cellphone number: 0036 20 3313 707



## Work experience

### BOSCH Hungary Ltd. (2022.09 – 2022.12.) – Project Leader

---

I joined the department responsible for automotive steering systems and was assigned to a team handling torque sensor assembly. Although I received a great review at the end of my probation period and had a pleasant experience working there, I found the position to be too distant from the designing and creating aspects of engineering for me to be able to enjoy it.

### European Knowledge Centre Ltd. (2021.05 – 2022.09.) – Mechatronics engineer

---

- Project lead and lead developer – AGV project  
In this project, I took on the roles of mechanical and electrical design engineer and embedded software developer while managing other members' contribution to the project. Key contributions to the project from my part:
  - 3D design realization from the concept work of an industrial form designer, making a manufacturable and functional body for the robot.
  - Complete electronics design, from requirements specification to prototype board bring up activity with hardware debugging and version upgrades.
  - Firmware development on the two STM32 chips found on the main board in C++.
- Electronics engineer – UVC autonomous disinfection robot  
In this project, I supported the project owner with various contributions, mainly in the electrical field.
  - Developing the charger pistol for the robot.
  - Designing replacement ballast for the robot.
- Support engineer  
Tasks where I supported other engineers or performed various supporting duties.
  - Managing an in house 3D printer farm.
  - Overseeing the manufacturing process of the prototype's frame of the UVC robot.
  - Maintenance of the UVC robots in house and on site.

## Sagax Communications (2018.05. – 2021.05.) – Mechatronics engineer

---

- Application engineer – SDR system project  
In this project, I was in a key role and contributed in various ways. Key contributions:
  - Developing the embedded control panels for the RF multiplexer circuits.
  - Took part in architecture design.
  - Deploying system, system maintenance
- Electric engineer, embedded software developer – Tuner module development  
In this hardware development project I worked with a senior RF colleague and he made the RF components and related design specifications. Everything else was my task.
  - Design and layout from requirements list to prototype bring up activity
  - Firmware writing
  - Conducting lab measurements for performance evaluation
- Application engineer – Drone Detection and Range Finding  
I joined this project because of my hobby of drone building. Although my main contribution was to pilot the drones for the measurements, I took a key part in conducting them as well.
  - Created 3D design and printed the struts of the DF antennas.
  - System testing in lab and on field.

## Morgan Advanced Materials (2017.06. – 2017.09.) – Assistant engineer

---

Created technical drawings of high performance motor brushes from customer requests to printouts for line workers. Supported the daily tasks of the senior engineers.

## Education

### Mechatronics Engineer BSc (2020)

---

Budapest University of Technology and Economics.

Started as a mechanics engineer, changed in 3<sup>rd</sup> semester to mechatronics as I liked electronics and embedded programming more than I have met in pure mechanics tuition.

## Mentionable non-work projects

### Thesis Project

---

In this project, I had to develop an AGV. I got high recognition for this work, but I ran out of time, as the scope was too large. Keywords, key technologies:

- C/C++ RTOS, ESP32, BLE, WiFi, ATMEGA 328p, Arduino
- Altium, 4 layer PCB, master slave MCU architecture, kinematics motion control
- Servo motors, Stepper drivers, OLED display, BMS
- Mechanical robot arm design, 3D printable body design

### 3D printer building

---

In 2020, I started building my own 3D printer because my first printer reached the end of its lifetime. This printer is based on an open source project called HevORT. I forked the project, made my modifications and managed to build a high-end machine.

## Multicopter building

---

It started as a hobby when I got my first one and became a professional user when I started using it for work. I designed and built a 550 hexacopter that could carry a considerable payload. This was necessary for one of my professional projects. I tried to get into the agricultural branch of the drone technology, successfully generating a survey of a 5-hectare field.

## Platform independent app development

---

Developed an Android IOS and web-supported application that has educational purposes. I came up with this idea a while ago and the opportunity came for me to make it into reality. When complete, you will find it on Google Play as "Nine Dimensions".

## Technology and Tools

### 3D CAD design and related

---

- Autodesk Inventor, SOLIDWORKS, Ultimaker CURA, Autodesk AutoCAD, CADQuery

### ECAD design

---

- Altium Designer and Altium 365 platform, SOLIDWORKS integration, LTSpice

### IDEs

---

- Visual Studio, Visual Studio Code

### Coding

---

- Git
- C/C++, C#, Python, Dart

### Misc

---

- ATmega, STM32, ESP32
- 
- Advanced Windows and Linux user
- Advanced Office user

## Languages

Hungarian (mother tongue), English (fluent, B2 certificate), German (moderate, C1 certificate)